

Current Sensor

Product Series: STK-CTS/P5
STK-25CTS/P5
STK-32CTS/P5
Part number: STK-40CTS/P5
STK-50CTS/P5
Version: Ver1.7



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1. Description

The STK-CTS/P series current sensor is based on TMR (tunnel magnetoresistance) technology and open-loop design. It is suitable for DC, AC pulsed and any kind of irregular current measurement under the isolated conditions.

Typical applications

- AC Variable speed drives
- Inverter
- Electric welder power supply
- Switched model power supplies (SMPS)

General parameter

Parameter	Symbol	Unit	Value
Working temperature	T_A	°C	-40 ~ 105
Storage temperature	T_stg	°C	-40 ~ 105
Mass	m	g	10
Maximum traverse temperature	T_mt	°C	105
Remark 1: The product will not be damaged when used at 105 °C			

Absolute maximum rating

Parameter	Symbol	Unit	Value
Supply voltage	Vcc	V	6
ESD rating (HBM)	U _{ESD}	kV	4

Remark 2: the unrecoverable damage may occur when the product works on the conditions over the absolute maximum ratings. Long-time working on the absolute maximum ratings may cause the degradation on performance and reliability.

Isolation parameter

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC test 50Hz/1 min	U _d	kV	4	
Impulse withstand voltage 1.2/50μs	U _w	kV	6	
Clearance distance (pri. -sec)	d _{CI}	mm	> 8	Space shortest distance
Creepage distance (pri. -sec)	d _{Cp}	mm	> 8	Shortest distance along the body
Shell material			V0 according to UL 94	

2. Electrical data STK-25CTS/P5

Condition: $T_A = 25^\circ\text{C}$, $V_{cc} = 5 \text{ V}$

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current	I_{pn}	A	-10		10	
Primary current measuring range	I_{pm}	A	-25		25	
Supply voltage	V_{cc}	V	4.75	5	5.25	
Current consumption	I_{cc}	mA		5	10	
Rated output voltage	V_{FS}	V		± 0.8		$(V_{out} @ \pm I_{pn}) - V_{off}$
Internal output resistance	R_{out}	Ω		1		$@V_{out}$
Quiescent voltage	V_{off}	V	2.48	2.5	2.52	$V_{out} @ 0 \text{ A}$
Theoretical gain	G_{th}	mV/A		80		0.8 V @ I_{pn}
Non-linearity	Non-L	% I_{pn}		0.5		$\pm I_{pn}$
reaction time	t_{ra}	μs		0.5		$@10\% \text{ of } I_{PN}$
Step response time	t_{res}	μs		1		$@90\% \text{ of } I_{PN}$
Delay time	t_{delay}	μs		1		$@400 \text{ kHz}$
-3dB band width	BW	kHz		400		Back-end non-RC circuit
Noise DC ~ 10 kHz DC ~ 100 kHz	V_{noise}	mVpp		15 25		
Accuracy @ RT	X	% of I_{pm}	-0.8		0.8	$@ 25^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 0.2 \text{ A}$
Accuracy	X_TRange	% of I_{pm}	-1.5		1.5	$@ -40^\circ\text{C} \sim 85^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 0.375 \text{ A}$
Accuracy	X_TRange	% of I_{pm}	-3		3	$@ 85^\circ\text{C} \sim 105^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 0.75 \text{ A}$

Note:

1. Accuracy @ RT,X = $((V_{out} @ I_n @ 25^\circ\text{C}) - (G_{fit} * I_n + V_{off} @ 25^\circ\text{C})) / V_{FS}$, Here I_n is the current test current. G_{fit} is the normal temperature fitting gain.
2. Accuracy,X_TRange = $((V_{out} @ I_n @ T_x) - (G_{fit}@25^\circ\text{C} * I_n + V_{off} @ 25^\circ\text{C})) / V_{FS}$, The fitting gain of the product at $G_{fit}@25^\circ\text{C}$ is 25 °C.

3. Electrical data STK-32CTS/P5

Condition: $T_A = 25^\circ\text{C}$, $V_{cc} = 5 \text{ V}$

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current	I_pn	A	-12.8		12.8	
Primary current measuring range	I_pm	A	-32		32	
Supply voltage	Vcc	V	4.75	5	5.25	
Current consumption	Icc	mA		5	10	
Rated output voltage	V_FS	V		±0.8		(Vout @ ±I_pn) – Voff
Internal output resistance	R_out	Ω		1		@Vout
Quiescent voltage	Voff	V	2.48	2.5	2.52	Vout @ 0 A
Theoretical gain	G_th	mV/A		62.5		0.8 V @ I_pn
Non-linearity	Non-L	%I_pn		0.5		±I_pn
reaction time	t_ra	μs		0.5		@10% of I_PN
Step response time	t_res	μs		1		@90% of I_PN
Delay time	t_delay	μs		1		@400 kHz
-3dB band width	BW	kHz		400		Back-end non-RC circuit
Noise DC ~ 10 kHz DC ~ 100 kHz	Vnoise	mVpp		15 25		
Accuracy @ RT	X	% of I_pm	-0.8		0.8	@ 25°C When I_pn < I < I_pm Δ I (max) ≤ 0.256A
Accuracy	X_TRange	% of I_pm	-1.5		1.5	@ -40°C ~ 85°C When I_pn < I < I_pm Δ I (max) ≤ 0.48A
Accuracy	X_TRange	% of I_pm	-3		3	@ 85°C ~ 105°C When I_pn < I < I_pm Δ I (max) ≤ 0.96A

Note:

1. Accuracy @ RT,X = ((Vout @ In @ 25°C) – (G_fit * In+Voff @ 25°C)) / V_FS, Here In is the current test current. G_fit is the normal temperature fitting gain.
2. Accuracy,X_TRange = ((Vout @ In @ T_x) – (G_fit@25°C * In+Voff @ 25°C)) / V_FS, The fitting gain of the product at G_fit@25 °C is 25 °C.

4. Electrical data STK-40CTS/P5

Condition: T_A = 25°C, Vcc = 5 V

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current	I_pn	A	-16		16	
Primary current measuring range	I_pm	A	-40		40	

Supply voltage	Vcc	V	4.75	5	5.25	
Current consumption	Icc	mA		5	10	
Rated output voltage	V_FS	V		±0.8		(Vout @ ±I_pn) – Voff
Internal output resistance	R_out	Ω		1		@Vout
Quiescent voltage	Voff	V	2.48	2.5	2.52	Vout @ 0 A
Theoretical gain	G_th	mV/A		50		0.8 V @ I_pn
Non-linearity	Non-L	%I_pn		0.5		±I_pn
reaction time	t_ra	μs		0.5		@10% of I_PN
Step response time	t_res	μs		1		@90% of I_PN
Delay time	t_delay	μs		1		@400 kHz
-3dB band width	BW	kHz		400		Back-end non-RC circuit
Noise DC ~ 10 kHz	Vnoise	mVpp		15		
DC ~ 100 kHz				25		
Accuracy @ RT	X	% of I_pm	-0.8		0.8	@ 25°C When I_pn < I < I_pm Δ I (max) ≤ 0.32A
Accuracy	X_TRange	% of I_pm	-1.5		1.5	@ -40°C ~ 85°C When I_pn < I < I_pm Δ I (max) ≤ 0.60A
Accuracy	X_TRange	% of I_pm	-3		3	@ 85°C ~ 105°C When I_pn < I < I_pm Δ I (max) ≤ 1.2A

Note:

1. Accuracy @ RT,X = ((Vout @ In @ 25°C) – (G_fit * In+Voff @ 25°C)) / V_FS, Here In is the current test current. G_fit is the normal temperature fitting gain.
2. Accuracy,X_TRange = ((Vout @ In @ T_x) – (G_fit@25°C * In+Voff @ 25°C)) / V_FS, The fitting gain of the product at G_fit@25 °C is 25 °C.

5. Electrical data STK-50CTS/P5

Condition: $T_A = 25^\circ\text{C}$, $V_{cc} = 5 \text{ V}$

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current	I_{pn}	A	-20		20	
Primary current measuring range	I_{pm}	A	-50		50	
Supply voltage	V_{cc}	V	4.75	5	5.25	
Current consumption	I_{cc}	mA		5	10	
Rated output voltage	V_{FS}	V		± 0.8		$(V_{out} @ \pm I_{pn}) - V_{off}$
Internal output resistance	R_{out}	Ω		1		$@V_{out}$
Quiescent voltage	V_{off}	V	2.48	2.5	2.52	$V_{out} @ 0 \text{ A}$
Theoretical gain	G_{th}	mV/A		40		0.8 V @ I_{pn}
Non-linearity	Non-L	% I_{pn}		0.5		$\pm I_{pn}$
reaction time	t_{ra}	μs		0.5		$@10\% \text{ of } I_{PN}$
Step response time	t_{res}	μs		1		$@90\% \text{ of } I_{PN}$
Delay time	t_{delay}	μs		1		$@400 \text{ kHz}$
-3dB band width	BW	kHz		400		Back-end non-RC circuit
Noise DC ~ 10 kHz DC ~ 100 kHz	V_{noise}	mVpp		15 25		
Accuracy @ RT	X	% of I_{pm}	-0.8		0.8	$@ 25^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 0.4 \text{ A}$
Accuracy	X_TRange	% of I_{pm}	-1.5		1.5	$@ -40^\circ\text{C} \sim 85^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 0.75 \text{ A}$
Accuracy	X_TRange	% of I_{pm}	-3		3	$@ 85^\circ\text{C} \sim 105^\circ\text{C}$ When $I_{pn} < I < I_{pm}$ $\Delta I \text{ (max)} \leqslant 1.5 \text{ A}$

Note:

1. Accuracy @ RT,X = $((V_{out} @ I_n @ 25^\circ\text{C}) - (G_{fit} * I_n + V_{off} @ 25^\circ\text{C})) / V_{FS}$, Here I_n is the current test current. G_{fit} is the normal temperature fitting gain.
2. Accuracy,X_TRange = $((V_{out} @ I_n @ T_x) - (G_{fit}@25^\circ\text{C} * I_n + V_{off} @ 25^\circ\text{C})) / V_{FS}$, The fitting gain of the product at $G_{fit}@25^\circ\text{C}$ is 25 °C.

6. Frequency band width

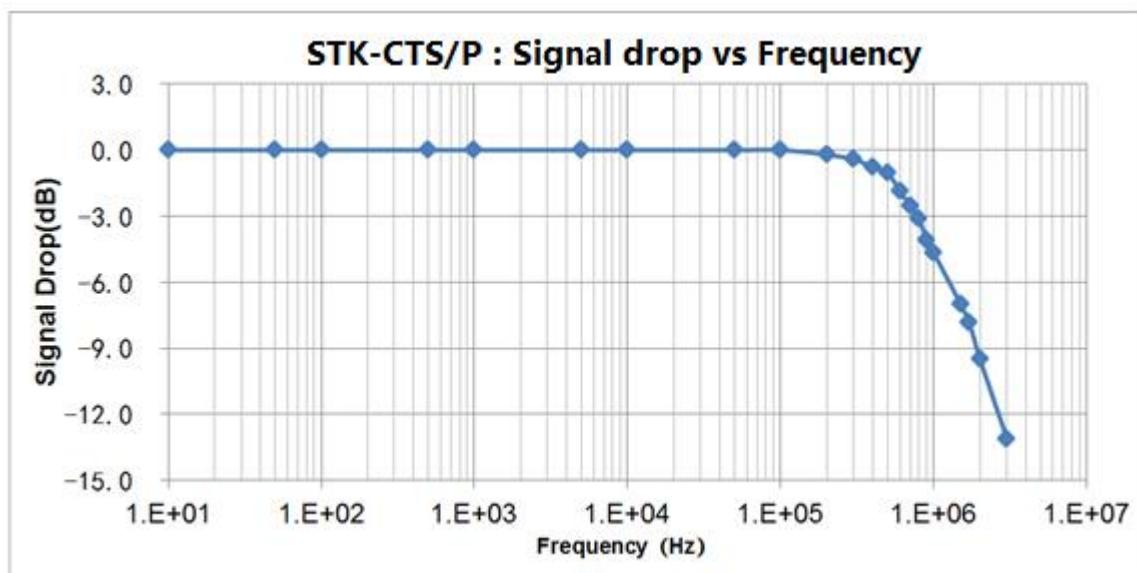


Fig.1 the band width of STK-CTS/P series current sensors. The bandwidth of the sensor is in the range of DC ~400 kHz (-3 dB).

7. Response time & noise with typical circuit

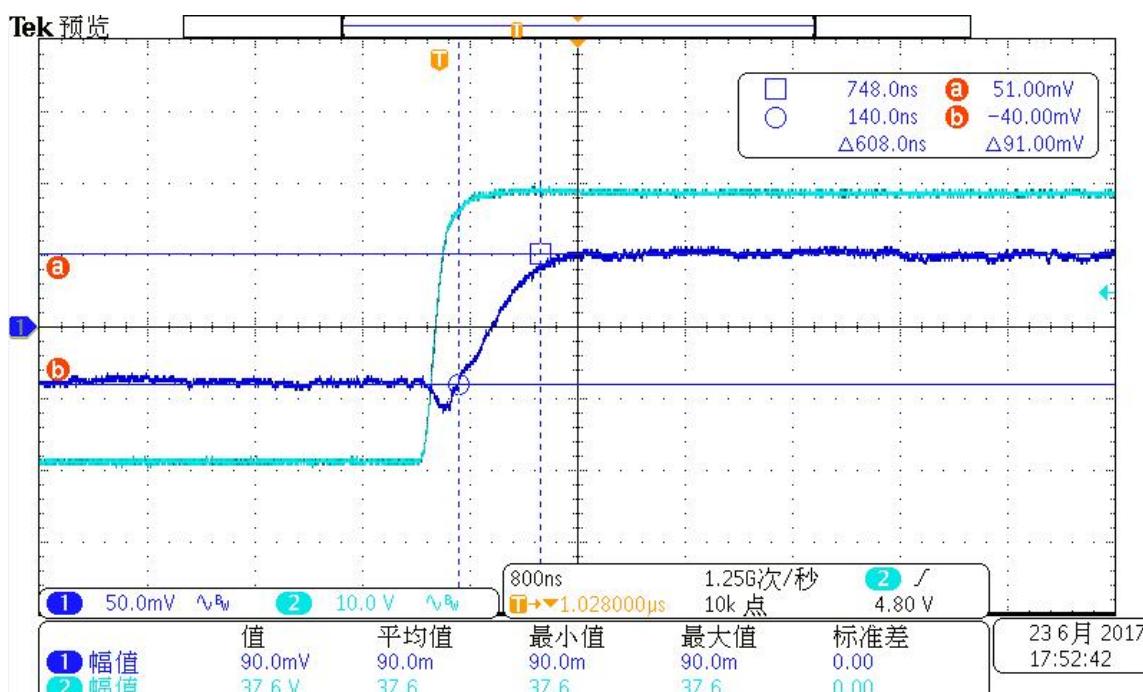


Fig.2 the step response time of STK-CTS/P current sensors. The light blue is primary current, while the dark blue is output signal of current sensor. The delay from 90% of the original current signal to 90% of the output of the sensor is less than 1us.

8. Frequency delay performance

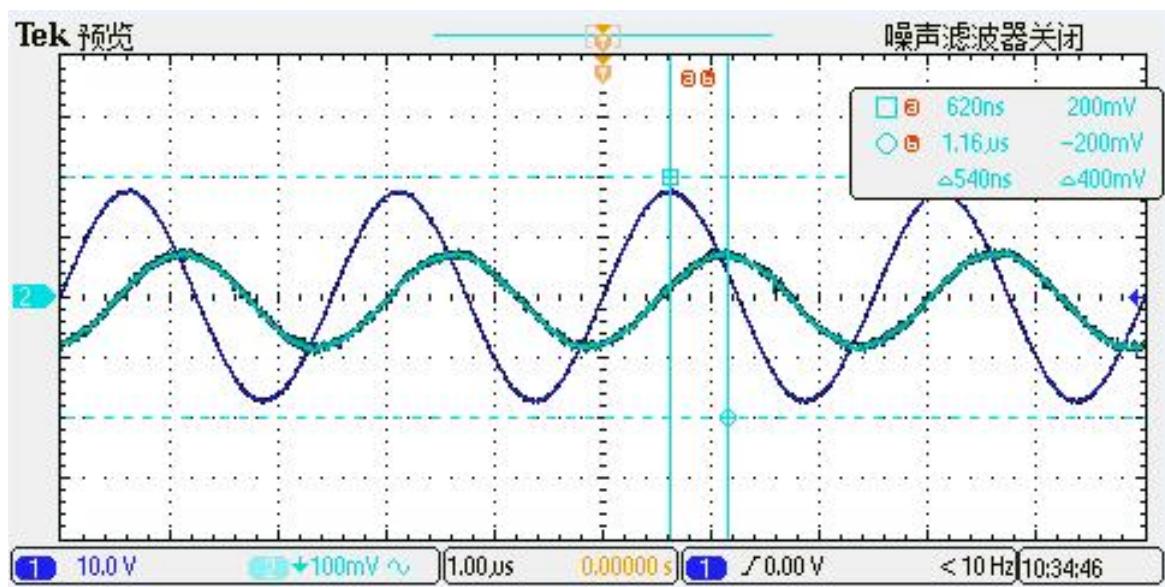


Fig.3 when detection the primary current with a frequency of 400 kHz. The typical results of the output of STK-CTS/P current sensor on the primary current delay characteristics. The delay time from primary current (light blue) to the output of the sensor (dark blue) is less than μ s.

9. STK-CTS/P5 Dimensions & Pins & Footprint

